

# Button Input: On/off state change

Living with the Lab  
Gerald Recktenwald  
Portland State University  
gerry@pdx.edu

# User input features of the fan

- Potentiometer for speed control
  - ❖ Continually variable input makes sense for speed control
  - ❖ Previously discussed
- Start/stop
  - ❖ Could use a conventional power switch
  - ❖ Push button (momentary) switch
- Lock or limit rotation angle
  - ❖ Button click to hold/release fan in one position
  - ❖ Potentiometer to set range limit

# Conventional on/off switch

## Basic light switch or rocker switch

- ❖ Makes or breaks connection to power
- ❖ Switch stays in position: On or Off
- ❖ Toggle position indicates the state
- ❖ NOT in the Arduino Inventors Kit



Image from sparkfun.com

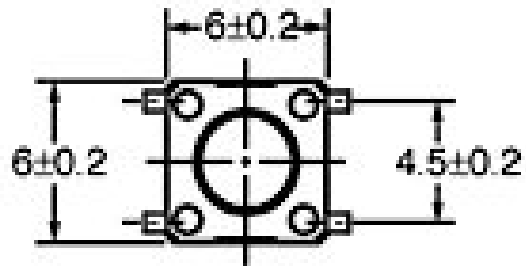
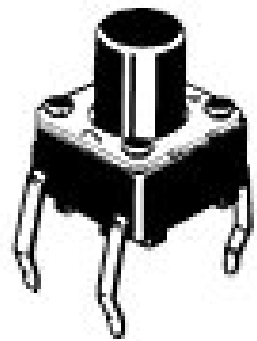
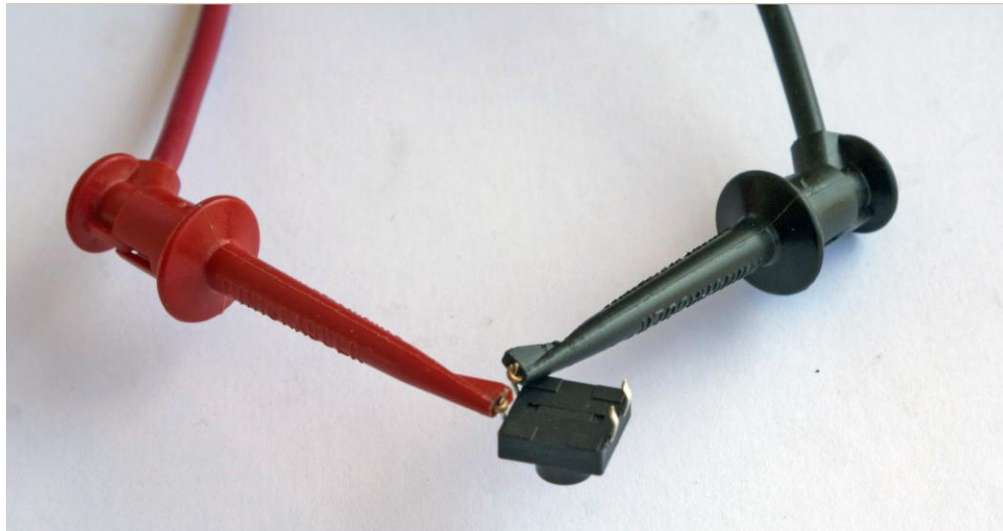


Image from lowes.com

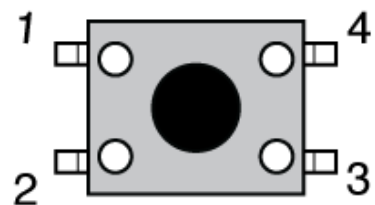
# How does a button work?

- Simple switch schematic
- Use DMM to measure open/closed circuit
- Map the pin states

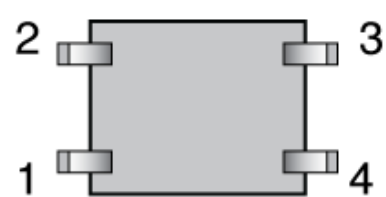
# Measure Open and Closed Circuits



Top View



Bottom View



Measured Resistance ( $\Omega$ )

Connect Pins	Measured Resistance ( $\Omega$ )	
	When not pressed	When pressed
1 and 2		
1 and 3		
1 and 4		
2 and 3		

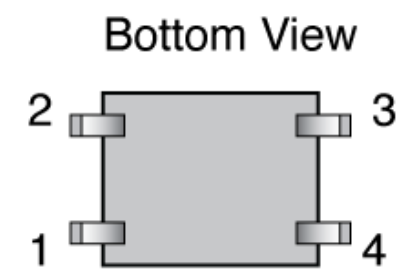
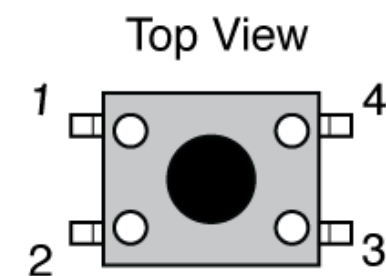
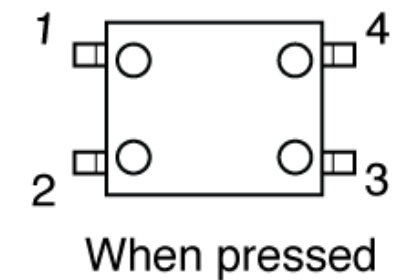
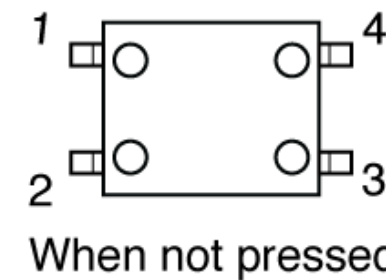
# Measure Open and Closed Circuits

## Data from Measurements:

Connect Pins	Measured Resistance ( $\Omega$ )	
	When not pressed	When pressed
1 and 2		
1 and 3		
1 and 4		
2 and 3		

## Sketch Connections:

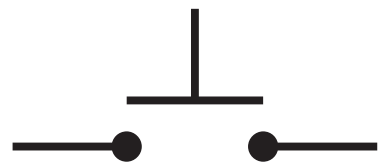
Draw lines between connectors



# Push Button Switches

- A momentary button is a “Biased Switch”
- Pushing the button changes state
- State is reversed (return to biased position) when button is released
- Two types
  - NO: normally open
  - NC: normally closed

Normally Open

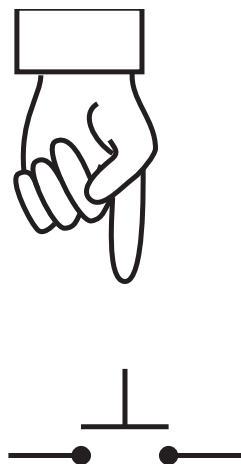


Normally Closed

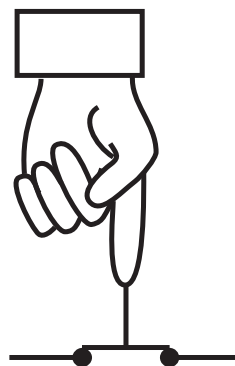


# Momentary or push-button switches

- Normally open
  - ❖ electrical *contact is made* when button is pressed
- Normally closed
  - ❖ electrical *contact is broken* when button is pressed
- Internal spring returns button to its un-pressed state



Open



Closed



Image from sparkfun.com



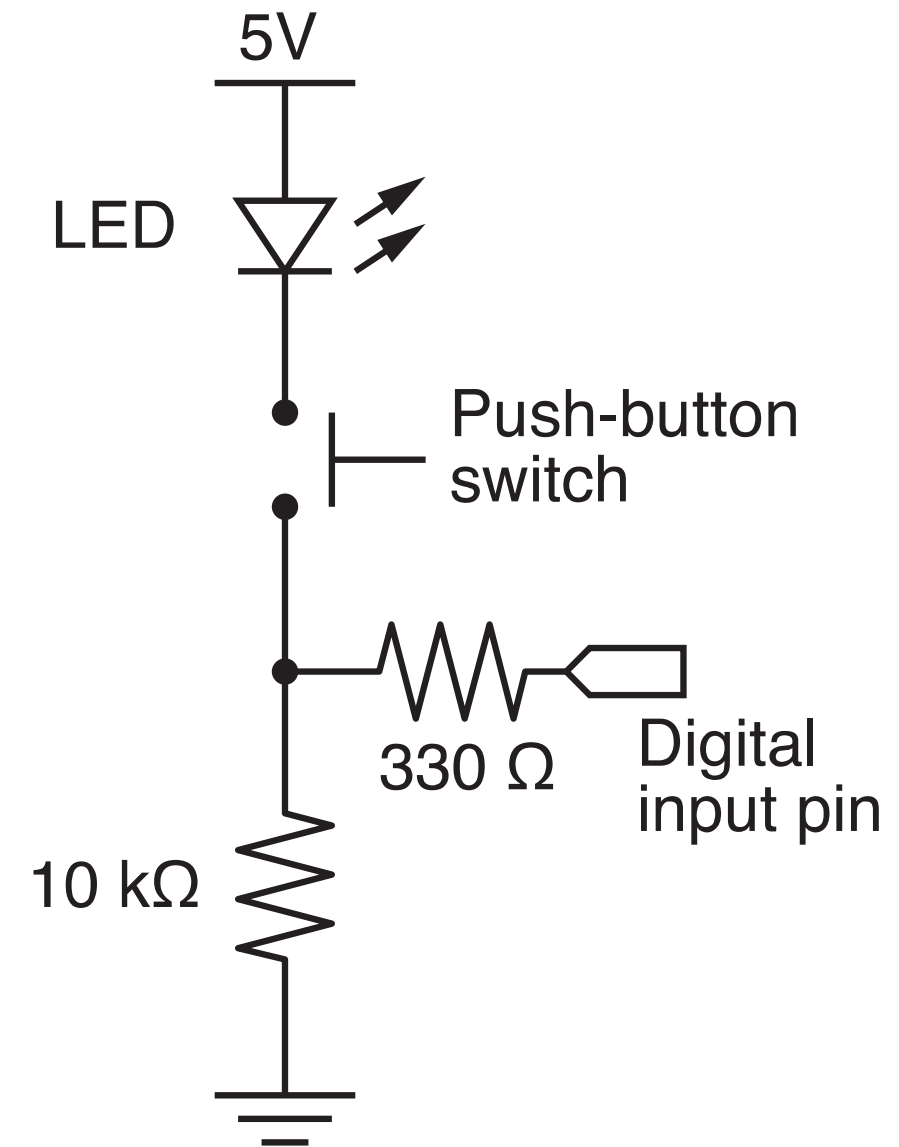
# Putting buttons into action

1. Build the circuit: same one is used for all examples
  - a. Test with LED on/off
  - b. LED is only controlled by the button, not by Arduino code
2. Create a “wait to start” button
  - a. Simplest button implementation
  - b. Execution is blocked while waiting for a button click
3. Use an interrupt handler
  - a. Most sophisticated: Don't block execution while waiting for button input
  - b. Most sophisticated: Requires good understanding of coding
  - c. Requires “de-bouncing”
  - d. Not too hard to use as a black box

# Momentary Button and LED Circuit

## Digital input with a *pull-down* resistor

- ❖ When switch is open (button not pressed):
  - ▶ Digital input pin is tied to ground
  - ▶ No current flows, so there is no voltage difference from input pin to ground
  - ▶ Reading on digital input is LOW
- ❖ When switch is closed (button is pressed):
  - ▶ Current flows from 5V to ground, causing LED to light up.
  - ▶ The 10k resistor limits the current draw by the input pin.
  - ▶ The 330Ω resistor causes a large voltage drop between 5V and ground, which causes the digital input pin to be closer to 5V

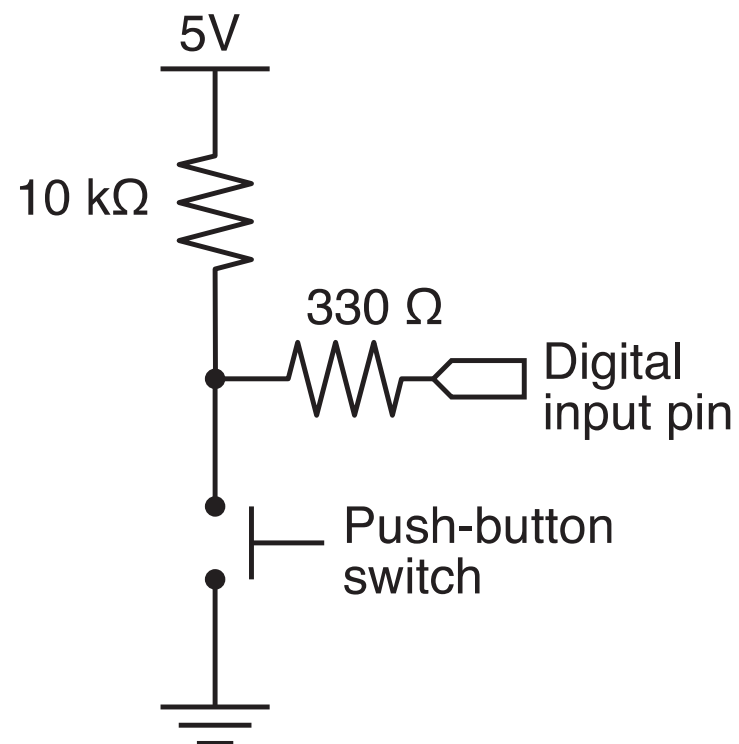


# Technical Note

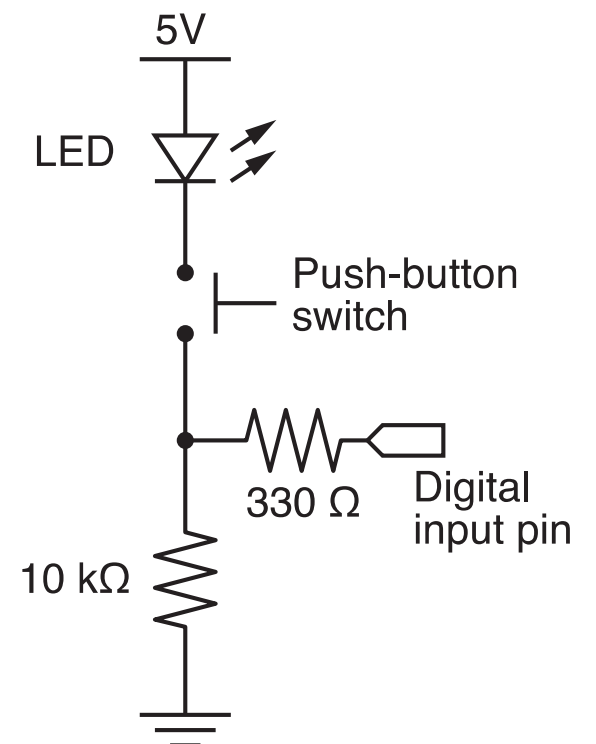
Usually we do not include an LED directly in the button circuit. The following diagrams show plan button circuits with pull-up and pull-down resistors. In these applications, the pull-up or pull-down resistors should be 10k. Refer to Lady Ada Tutorial #5:

❖ <http://www.ladyada.net/learn/arduino/lesson5.html>

Pull-up resistor:



Pull-down resistor:



# Programs for the LED/Button Circuit

## 1. Continuous monitor of button state

- ❖ Program is completely occupied by monitoring the button
- ❖ Used as a demonstration — not practically useful

## 2. Wait for button input

## 3. Interrupt Handler

## 4. All three programs use the same electrical circuit

# Continuous monitor of button state

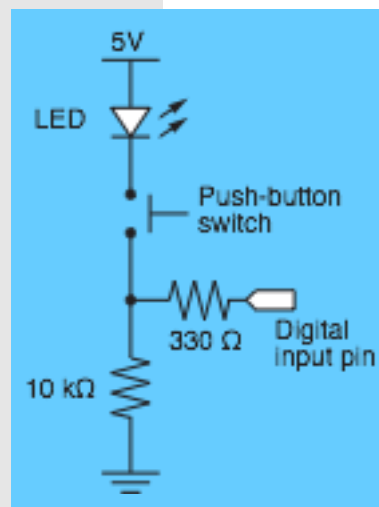
```
int button_pin = 4;      // pin used to read the button

void setup() {
  pinMode( button_pin, INPUT);
  Serial.begin(9600);    // Button state is sent to host
}

void loop() {
  int button;
  button = digitalRead( button_pin );

  if ( button == HIGH ) {
    Serial.println("on");
  } else {
    Serial.println("off");
  }
}
```

Serial monitor shows  
a continuous stream  
of “on” or “off”



This program *does not* control the LED

# Programs for the LED/Button Circuit

## 1. Continuous monitor of button state

- ❖ Program is completely occupied by monitoring the button
- ❖ Used as a demonstration — not practically useful

## 2. Wait for button input

- ❖ Blocks execution while waiting
- ❖ May be useful as a start button

## 3. Interrupt Handler

## 4. All three programs use the same electrical circuit

# Wait for button input

```
int button_pin = 4;           // pin used to read the button

void setup() {
  int start_click = LOW;     // Initial state: no click yet
  pinMode( button_pin, INPUT);
  Serial.begin(9600);

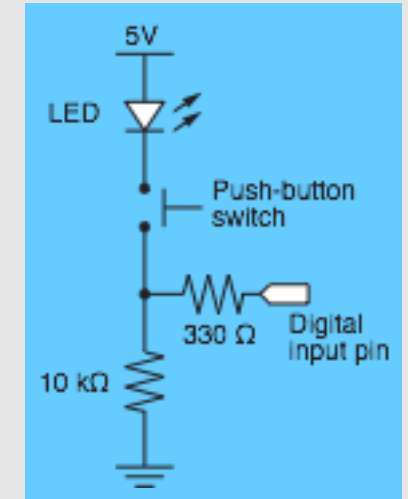
  while ( !start_click ) {
    start_click = digitalRead( button_pin );
    Serial.println("Waiting for button press");
  }
}

void loop() {
  int button;

  button = digitalRead( button_pin );
  if ( button == HIGH ) {
    Serial.println("on");
  } else {
    Serial.println("off");
  }
}
```

Same loop() function  
as in the preceding  
sketch

while loop  
continues as long  
as start\_click is  
**FALSE**



# Programs for the LED/Button Circuit

## 1. Continuous monitor of button state

- ❖ Program is completely occupied by monitoring the button
- ❖ Used as a demonstration — not practically useful

## 2. Wait for button input

- ❖ Blocks execution while waiting
- ❖ May be useful as a start button

## 3. Interrupt Handler

- ❖ Most versatile
- ❖ Does not block execution
- ❖ Interrupt is used to change a flag that indicates state
- ❖ Regular code in loop function checks the state of the flag

## 4. All three programs use the same electrical circuit



# Interrupt handler for button input

```
int button_interrupt = 0; // Interrupt 0 is on pin 2 !!
int toggle_on = false; // Button click switches state

void setup() {
  Serial.begin(9600);
  attachInterrupt( button_interrupt, handle_click, RISING); // Register handler
}

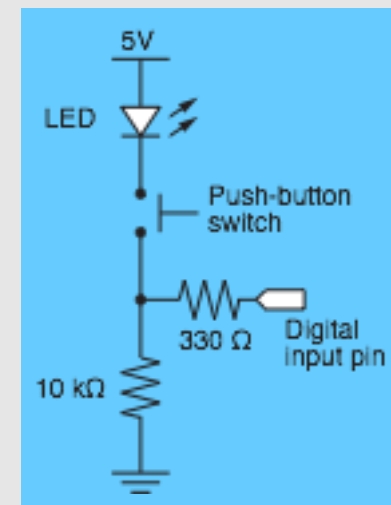
void loop() {
  if ( toggle_on ) {
    Serial.println("on");
  } else {
    Serial.println("off");
  }
}

void handle_click() {

  static unsigned long last_interrupt_time = 0; // Zero only at start
  unsigned long interrupt_time = millis(); // Read the clock

  if ( interrupt_time - last_interrupt_time > 200 ) { // Ignore when < 200 msec
    toggle_on = !toggle_on;
  }

  last_interrupt_time = interrupt_time;
}
```



# Interrupt handler for button input

```
int button_interrupt = 0; // Interrupt 0 is on pin 2 !!
int toggle_on = false; // Button click switches state

void setup() {
  Serial.begin(9600);
  attachInterrupt( button_interrupt, handle_click, RISING); // Register handler
}

Serial.println("on");
} else {
  Serial.println("off");
}
}

void handle_click() {

  static unsigned long last_interrupt_time = 0; // Zero only at start
  unsigned long interrupt_time = millis(); // Read the clock

  if ( interrupt_time - last_interrupt_time > 200 ) { // Ignore when < 200 msec
    toggle_on = !toggle_on;
  }

  last_interrupt_time = interrupt_time;
}
```

Interrupt handler must be registered when program starts

button\_interrupt is the ID or number of the interrupt. It must be 0 or 1

A RISING interrupt occurs when the pin changes from LOW to HIGH

The interrupt handler, handle\_click, is a user-written function that is called when an interrupt is detected

# Interrupt handler for button input

```
int button_interrupt = 0; // Interrupt 0 is on pin 2 !!
int toggle_on = false; // Button click switches state

void setup() {
  Serial.begin(9600);
  attachInterrupt( button_interrupt, handle_click, RISING); // Register handler
}

void loop() {
  if ( toggle_on ) {
    Serial.println("on");
  } else {
    Serial.println("off");
  }
}

void handle_click() {

  static unsigned long last_interrupt_time = 0; // Zero only at start
  unsigned long interrupt_time = millis(); // Read the clock

  if ( interrupt_time - last_interrupt_time > 200 ) { // Ignore when < 200 msec
    toggle_on = !toggle_on;
  }

  last_interrupt_time = interrupt_time;
}
```

`toggle_on` is a global variable that remembers the "state". It is either true or false (1 or 0).

The `loop()` function only checks the state of `toggle_on`. The value of `toggle_on` is set in the interrupt handler, `handle_click`.

The value of `toggle_on` is flipped only when a *true* interrupt even occurs. De-bouncing is described in the next slide.

# Interrupt handler for button input

```
int button_interrupt = 0; // Interrupt 0 is on pin 2 !!
int toggle_on = false; // Button click switches state

void setup() {
  Serial.begin(9600);
  attachInterrupt( button_interrupt, handle_click, RISING); // Register handler
}
```

```
void loop() {
  if ( toggle_on ) {
    Serial.println("on");
  } else {
    Serial.println("off");
  }
}
```

```
void handle_click() {
  static unsigned long last_interrupt_time = 0; // Zero only at start
  unsigned long interrupt_time = millis(); // Read the clock

  if ( interrupt_time - last_interrupt_time > 200 ) { // Ignore when < 200 msec
    toggle_on = !toggle_on;
  }

  last_interrupt_time = interrupt_time;
}
```

Value of a *static* variable is always retained

Use *long*: the time value in milliseconds can become large

Clock time when current interrupt occurs

Ignore events that occur in less than 200 msec from each other. These are likely to be mechanical bounces.

Save current time as the new "last" time

# Other references

## Ladyada tutorial

- ❖ Excellent and detailed
- ❖ <http://www.ladyada.net/learn/arduino/lesson5.html>

## Arduino reference

- ❖ Minimal explanation
  - ▶ <http://www.arduino.cc/en/Tutorial/Button>
- ❖ Using interrupts
  - ▶ <http://www.uchobby.com/index.php/2007/11/24/arduino-interrupts/>
  - ▶ <http://www.arduino.cc/en/Reference/AttachInterrupt>